Image feature extraction from the experimental semivariogram and its application to texture classification

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ABSTRACT - In this paper, we present a new procedure for texture classification of satellite images. Parameters derived from the experimental variogram are introduced and tested to determine if the classification of land cover classes is improved. We give a different treatment to the periodic directional variograms which are computed using an adaptive window size. Then, a stepwise analysis process is done to select the most discriminant features, and simultaneously eliminate correlated features. Finally, a validation test is made to quantify the usefulness of the proposed texture features in the discrimination of several urban areas and agricultural and forest areas, using QuickBird satellite images. The results show the usefulness of the features selected in performing image classification.

1. INTRODUCTION

Since its development in the mining industry geostatistics has been applied in different fields of study. However, in image analysis, and more specifically in texture analysis, the use of these techniques is relatively new. Different methods have been proposed to incorporate geostatistics to image analysis (see for example, Miranda et al. (1992, 1998), Chica-Olmo and Abarca-Hernandez (2000) or Maillard (2003)), with varying results. A well known tool used in geostatistics is the experimental semivariogram. From here on in this work we will be using the name variogram instead of experimental semivariogram.

For continuous variables, such as reflectance in a given waveband, the variogram is defined as half the average squared difference between values separated by a given lag h, where h is a vector, in both distance and direction, Atkinson and Lewis (2000).

$$\gamma(h) = \frac{1}{2N} \sum_{i=1}^{N} \left[Z(x_i) - Z(x_i + h) \right]^2$$
(1)

Function (1) relates semivariance to spatial separation and provides a concise and unbiased description of the scale and pattern of spatial variability, Curran (1988). Durrieu et al. (2005) show that some textures have variograms that reflect certain periodicity in the image. Variograms often increase continuously with lag distance, however, the variogram is not restricted to such monotonic behavior and decreasing segments or periodicity can be observed. This variogram structures are identified as "hole effect" structures, and can offer valuable information which shouldn't be discarded (Pyrcz et al., 2003). A periodic behavior indicates the existence of spatial structures in the images under study. At the same time this periodic characteristic of the variogram let us determine the window size to use. Different textures with their respective variogram curves can be seen in Figure 1:



Figure 1. Different textures with their respective variogram curves.

In this paper we determine that the range and the sill and other values of the variogram curve near the origin, provide useful information about the texture been studied. From these values, we determine different indices. In the cases where the variogram curve has a periodic behavior, more indices are extracted. Once these indices are obtained the most discriminant ones are chosen and a classification of the study area is made.

2. MATERIALS AND METHODS

2.1 Study area and data

The analysis was performed over two subsets of a QuickBird satellite image:

Subset 1: From the panchromatic band of the image (0.61 m/pixel) (Figure 2). The area studied is located to the north of the province of Valencia, (Spain), and it is dominated by agricultural land with the primary production being oranges, as well as some cereal crops. There are also pine forests, mostly at the hill sides, with some outcrops of pine trees between the cultivated land. Six types of land cover classes were differentiated in order to test the usefulness of the method: forest, not cultivated land, cultivated with crops, cultivated with orange trees, cultivated with degraded orange trees, and young orange trees.



Figure 2. Subset 1: image of cultivated land

Subset 2: It corresponds to the blue band of the same QuickBird image (2.4 m/pixel), resampled to 5 m/pixel, considered to be the most appropriate resolution for the average texture classes tested (Figure 3). This area contains a part of the city of Valencia. Four classes were defined: old urban areas, new building areas, facilities and industrial areas, parks and cultivated land.



Figure 3. Subset 2: image of part of the city of Valencia

2.2 Window size determination

To incorporate this concept first we have to treat the digital number of each pixel as a variable, and as a realization of a random spatial process, and in that case a variogram can be calculated in each pixels neighborhood window (Chen and Gong, 2004), which size is determined as follows:

The window size is an important parameter, due to the fact that has to be large enough to contain a representative part of the texture to which a single pixel belongs, but not as large as to include a part of an adjacent texture. In this study this issue is divided into two consecutive steps:

1) Omnidirectional Variogram:

A fixed window size of 30 pixels is used. This size was considered large enough to account for all the variability present in the texture. An omnidirectional variogram is computed over this window.

2) Directional or omnidirectional variogram:

We distinguish two cases according to the behaviour of the omnidirectional variogram computed in the first step, and the window size will be different depending on the result obtained.

- a) If the omnidirectional variogram presents periodicity, the size of the final window will be equal to the distance at which the second maximum value of the curve is reached. Over this window, eight directions are considered to compute the new variogram: 0°, 22.5°, 45°, 67.5°, 90°, 112.5°, 135° y 157.5°. Once these eight variograms are computed, the parameters are extracted from the variogram in the direction of maximum variability.
- b) If the omnidirectional variogram does not present periodicity, the window size will be the maximum possible, that is, 30 pixels. In this case, instead of a

directional variogram, the same omnidirectional variogram of the first step is used to extract the corresponding parameters.

2.3 Parameter extraction and selection

The indices computed were based on mean values, variances and simple ratios between values at the first lag up to the first maximum value of the variogram, second derivatives of the values at the first lag and different integrals. If the result is a periodic variogram, a second set of parameters is computed. We consider that a variogram is periodic if it has a first maximum, a first minimum and a second maximum. Then, new parameters based on integrals and ratios between the first and the second maximum are computed.

The parameters are divided into three categories:

a) <u>General parameters</u>: In this category there is the ratio of the variogram value in the first two lags. We also consider ratio of the first variogram value and the variance of the data as an estimation of the sill. We also compute the slope at the origin, and different derivatives using the first three to four variogram values.

$$Gp1 = \frac{Variance}{\gamma(h_1)}$$
$$Gp \ 3 = \frac{\gamma(h_2)}{\gamma(h_1)}$$
$$Gp4 = \frac{\gamma(h_2) - \gamma(h_1)}{h}$$

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b) <u>First maximum parameters</u>: Here we define the distance at which the expected range is reached, the mean of the values up to the expected range which we call the first maximum h_{max1} , the variance of these values and different integrals up to that value.

$$Fmp1 = h_{\max_{1}}$$

$$Fmp2 = \frac{1}{\max_{1}} \sum_{i=1}^{\max_{1}} \gamma(h_{i})$$

$$Fmp3 = \frac{1}{\max_{1}} \sum_{i=1}^{\max_{1}} (\gamma(h_{i}) - Fmp2)^{2}$$

c) <u>Second maximum parameters</u>: This last set of parameters incorporate information extracted from the variogram of the values from the first maximum up to the second maximum.

$$Smp1 = h_{\max_{2}} - h_{\max_{1}}$$

$$Smp5 = \frac{h}{2} \left(\gamma(h_{\max_{1}}) + 2 \left(\sum_{i=\max_{1}+1}^{\max_{2}-1} \gamma(h_{i}) \right) + \gamma(h_{\max_{2}}) \right)$$

A more complete description of the parameters used is available in Durrieu et al. (2005).

A low pass filter was applied over the original image and the result added to the set of the variogram parameters. The intention was to incorporate some information derived from the mean to the analysis, since the variogram provides only information regarding the spatial correlation of the data.

A supervised classification of the two images described in paragraph 2.1, was made. The method of maximum likelihood was applied to the two subsets. This method assumes that the statistics for each class in each band are normally distributed and calculates the probability that a given pixel belongs to a specific class. Each pixel is assigned to the class that has the highest probability. Training samples of each representative area were defined. Edges were not included in the analysis although they have a mayor role in classification errors Ferro et al. (2002).

3. RESULTS

The results of the classification of the urban area can be seen in Table 1. In this case, two analyses were made: (1) a classification with all the variogram derived indices in the first place, and (2) a classification adding the three visible spectral bands of the Quickbird image (resampled to 5 m.). Some control areas were determined in order to test the accuracy of the method. The parameters obtained from the variogram were compared with a well known texture analysis method, the cooccurrence matrix method, evaluating in each case the classification results. In the case of the cooccurrence matrix, eight parameters were used.

The results in the three analysis carried out are very similar. The best result obtained was an overall accuracy of 76.4% with the co-occurrence matrix method. With all three methods the old and new city areas were difficult to discriminate.

The results obtained in the classification of the agricultural area are shown in Table 2. In this case, the spectral bands were not included because it was considered that the information derived from the variogram was enough to give good results in a classification.

The results obtained comparing both methods are again very similar, although in this case the variogram method gives a better result, with an overall accuracy close to 84%. The parameters derived from the variogram provide a better result in those classes with regularity and structural patterns, such as orange trees.

	Urban areas						
	Semivariogram		Semivariogram+spectral bands		Co-occurrence Matrix		
	Producers	Users	Producers	Users	Producers	Users	
	accuracy	accuracy	accuracy	accuracy	accuracy	accuracy	
Old City	83.8	73.7	84.7	74.4	88.9	73.2	
New City	70.4	61.9	72.6	63.4	71.3	73.3	
Industrial zone	57.9	91.2	59.9	90.8	64.3	77.8	
Parks and gardens	81.5	82.1	83.2	88.4	81.4	86.9	
Overall	73.5		75.2		76.4		

Table1. Classification results of urban	areas comparing the semi	ivariogram, ser	mivariogram with	i spectral b	bands
	and co-occurrence matrix	methods			

	Agricultural land				
	Semiva	riogram	Co-occurrenceMatrix		
	Producers	Users	Producers	Users	
	accuracy	accuracy	accuracy	accuracy	
Crops	100.0	93.3	97.5	98.5	
Barren soil	94.2	100.0	99.3	98.8	
Orange groves	90.1	87.1	90.0	90.8	
Young orange groves	69.7	71.2	57.2	73.1	
Deg orange groves	62.6	64.4	77.1	52.7	
Pine trees	100.0	100.0	99.0	100.0	
Overall	83.9		82.9		

Table 2. Classification results comparing the semivariogram and co-occurrence methods.

4. CONCLUSIONS

The use of an adaptative window size maximizes the within class variation reducing the between class variation and therefore reducing the so called "edge effect".

The method proposed takes into consideration two cases:

a) variograms with periodic behavior where a direction is used.

b) variograms without periodic behavior where an omnidirectional variogram is used.

This distinction allowed us to better discriminate textures that present directionality or some kind of spatial structure as is the case of the orange groves from those textures that are more homogeneous as are barren soils.

The intention to discriminate between different types of orange groves (mature, young and degraded) did not work as well as expected, especially between young and degraded orange groves, that were confused with each other.

The parameters proposed are valid, specially in the cases of textures with some structure. The parameters that better discriminate are those that include the first value of the variogram in any of its combinations.

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